





Industrial Research Chair Control of Oilsands Processes

Process Data Analytics State of the art and applications in oil sands industry

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Outline

- Data Analytics State of the art
- Oil Sands Industry
- Process Data Analytics in Applications
- Analytics Toolboxes in Progress
- Conclusion



Data Analytics



Data Analytics

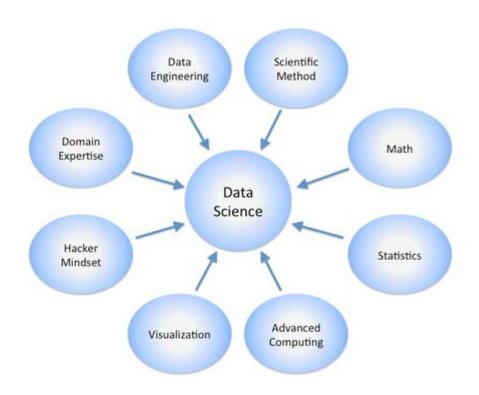








Data Science





History of Data Analytics

Analytics 1.0

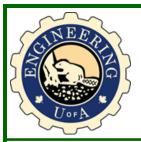
• Traditional Analytics (mid-1950s - 2000)

Analytics 2.0

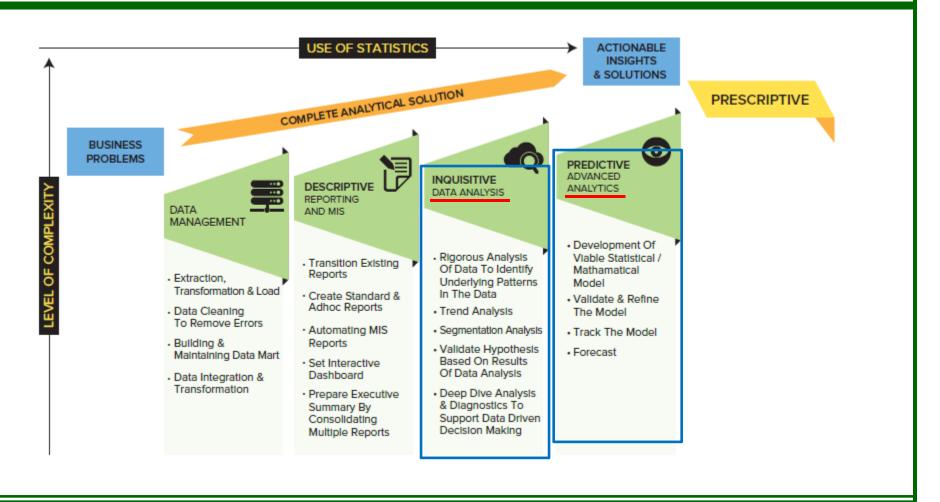
• Big Data (early 2000s - today)

Analytics 3.0

• Data Economy (future)

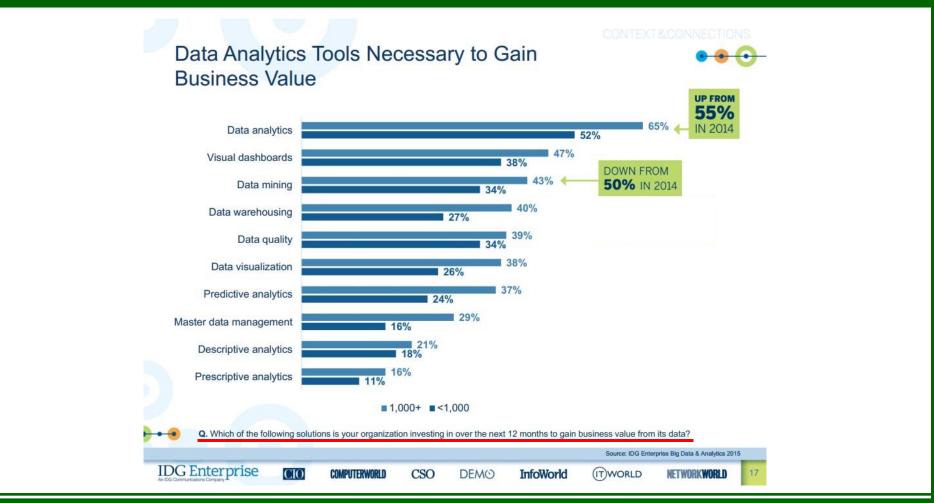


Data Analytics vs Data Analysis



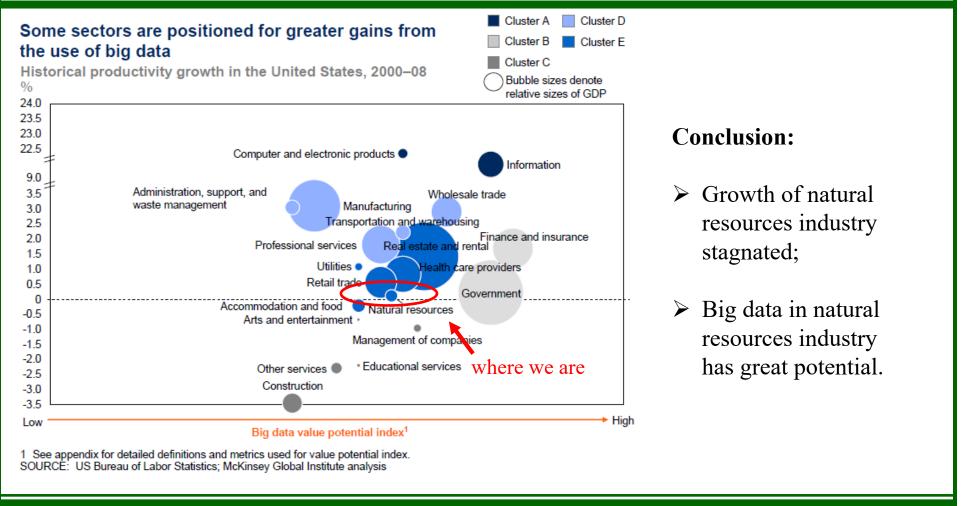


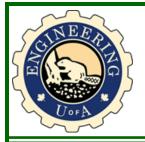
Increasing Trend of Data Analytics





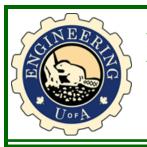
Application of Data Analytics: Engineering



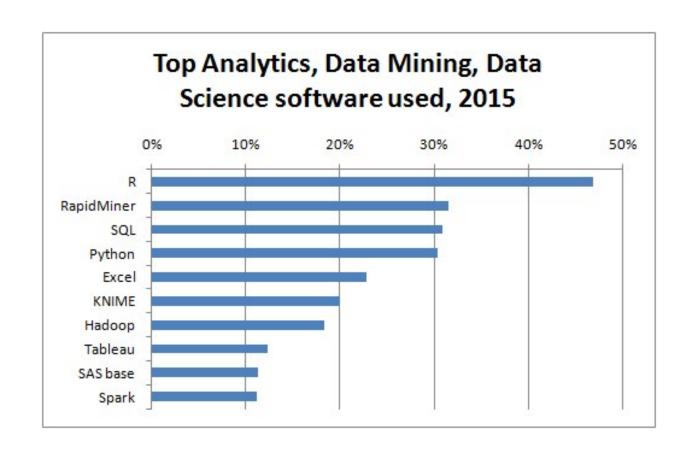


Typical Algorithms in Data Analytics

- Supervised learning
 - Regression: LASSO, Decision tree, PLS, MLR
 - > Classification: Logistic regression
 - ➤ Hybrid: Gaussian Process, Neural Network, SVM/SVR
 - **>** ...
- Unsupervised learning
 - ➤ Dimension Reduction: PCA
 - ➤ Clustering: k-means
 - **>** ...
- Inference
 - ➤ Maximum Likelihood, Expectation Maximization
 - ➤ Bayesian Method, Variational Bayesian, Bayesian Network
 - **>** ...



Data Analytics Software Platform and Toolboxes

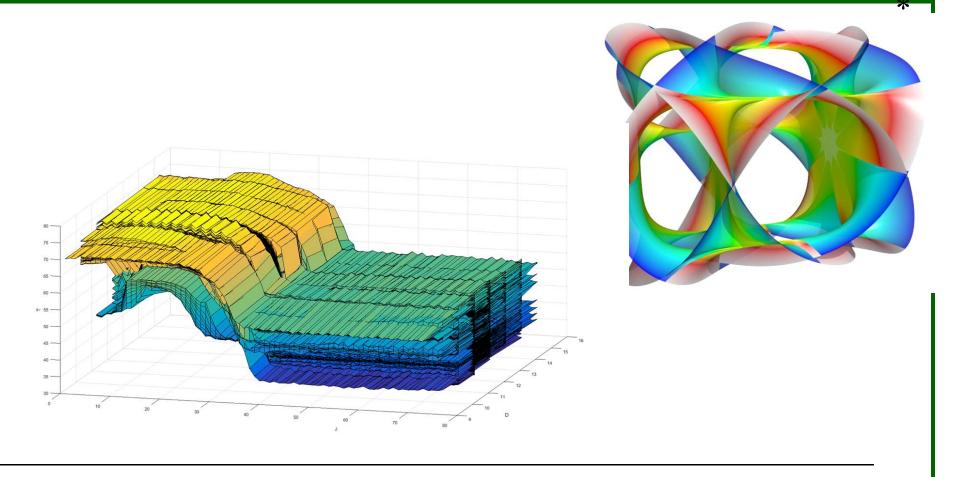




Process Data Analytics(Engineering)



High Dimensionality

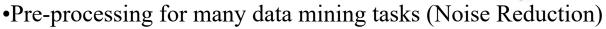




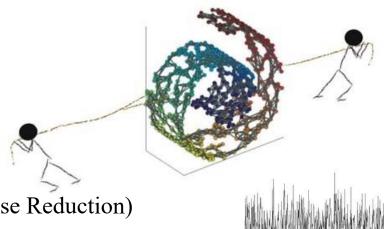
High Dimensionality of Data - "Decoding"

PCA/PLS/ICA and Applications:

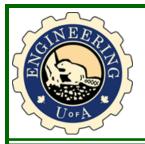
•Dimensionality Reduction



•Analyze data and to find patterns

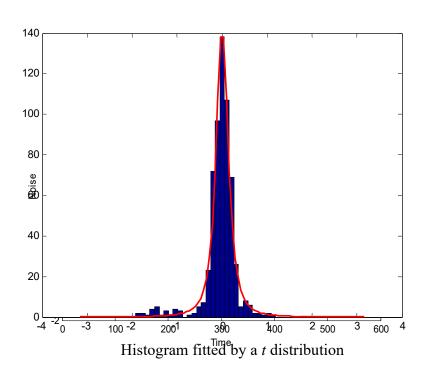


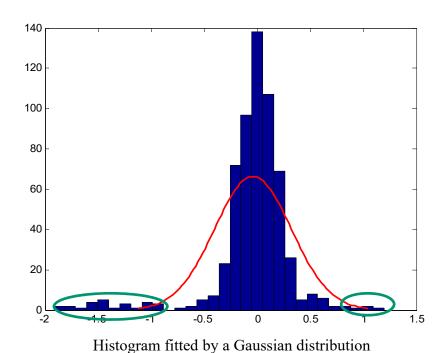




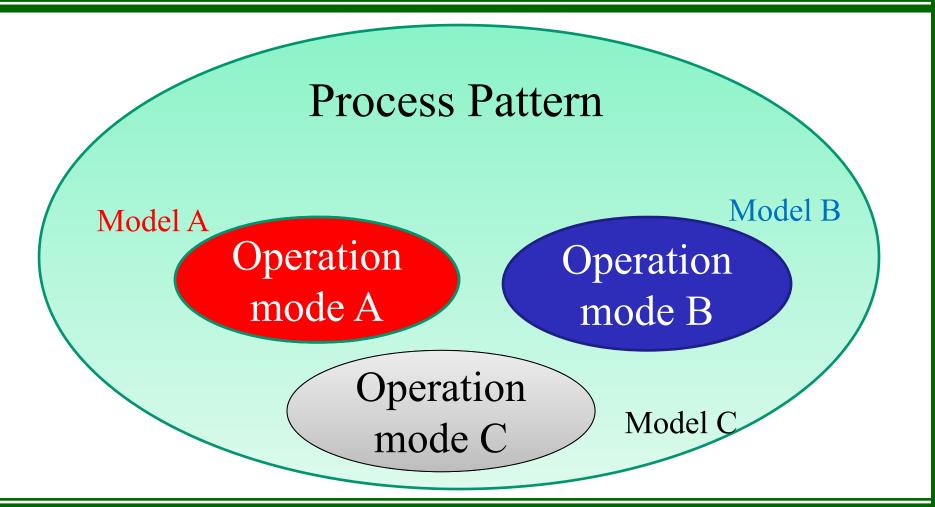
Robustness – Dealing with Irregular Data

Modeling the noise: Gaussian distribution vs others







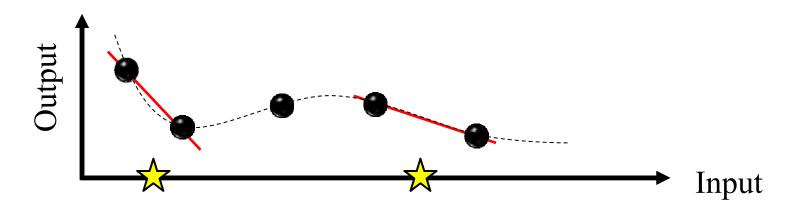




Nonlinearity – Local Solution

JIT modeling

- = Locally weighted modeling
- = Relevance-In-Space modeling
- = Lazy modeling

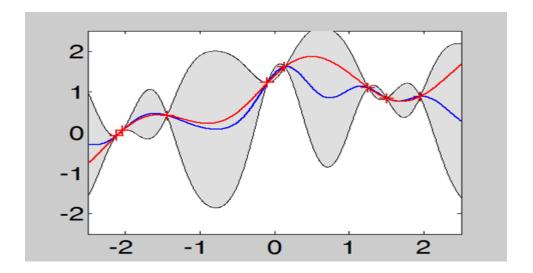




Nonlinearity – Gaussian Process

$$p(\mathbf{y}|\mathbf{X},l,\sigma^2) = \int p(\mathbf{y}|\mathbf{f},\mathbf{X},\sigma^2)p(\mathbf{f}|\mathbf{X},l) d\mathbf{f}$$

Analytical expression of likelihood exists





Time varying time delays

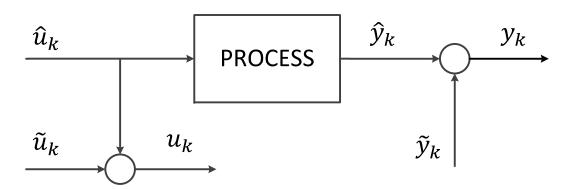
Multirate sampling with time Varying time-delays:

- Dual rate: fast rate input while slow rate output
- Time delay is varying at every sample



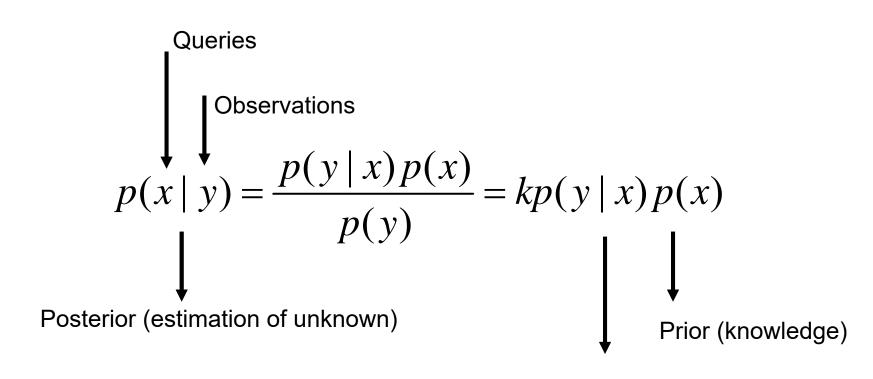
Errors-In-Variables (EIV)

- Noise-corrupted measurements: u_k , y_k
- Additive noise: \tilde{u}_k , \tilde{y}_k
- Unknown noise-free input and output: \hat{u}_k , \hat{y}_k





Process Knowledge - Bayes Methods



Likelihood (model fit)



Oil Sands



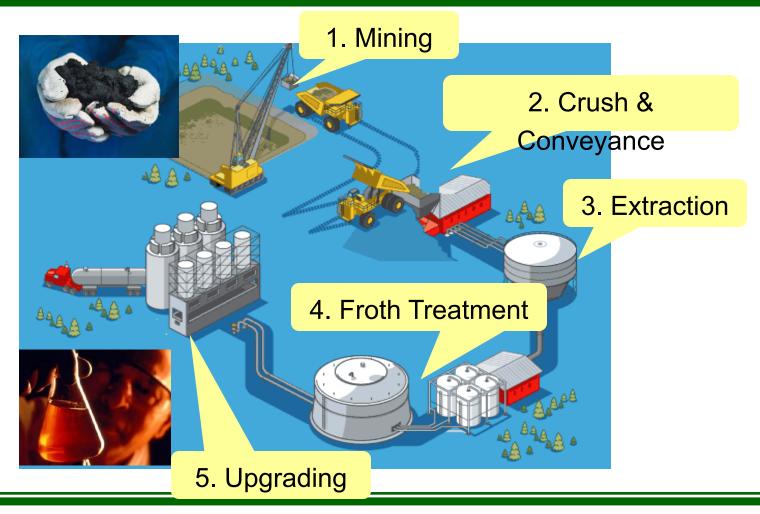
Canada's Oil Sands



- 141,000 square kilometres deposit
- 1.7 trillion barrels of bitumen
- 170 billion barrels recoverable
- second largest oil reserve
- 1.3 million barrels crude oil per day



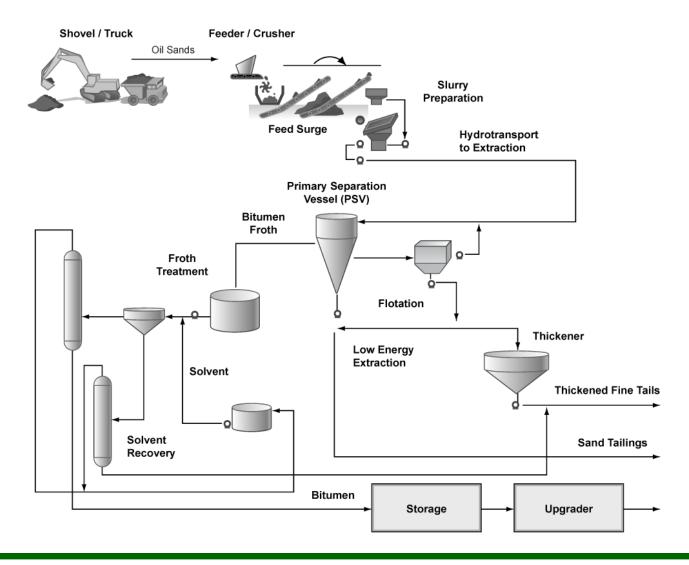
From Oil Sands to Sweat Crude Oil

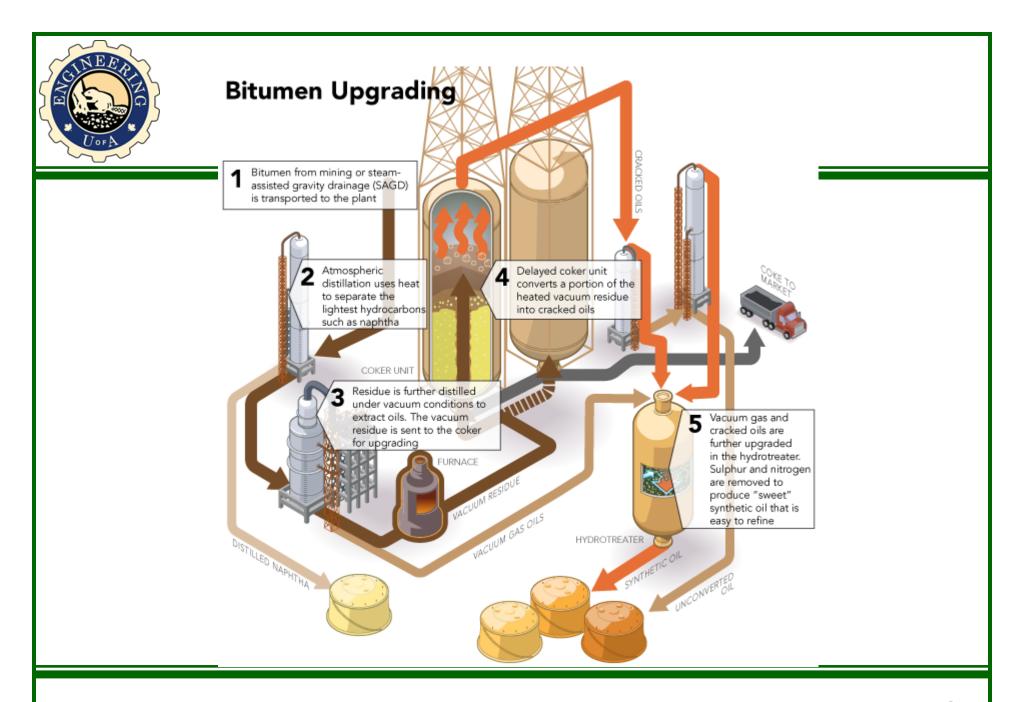


Source: http://www.ems.psu.edu/~pisupati/ACSOutreach/Oil_Sands.html



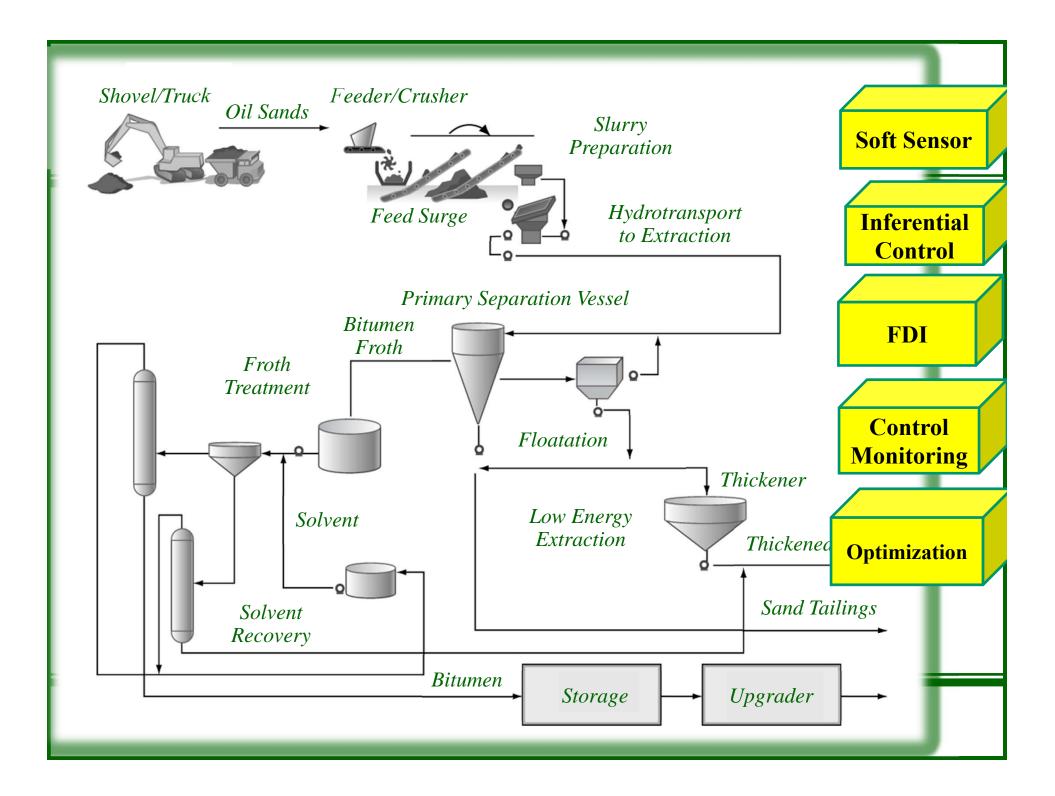
Extraction





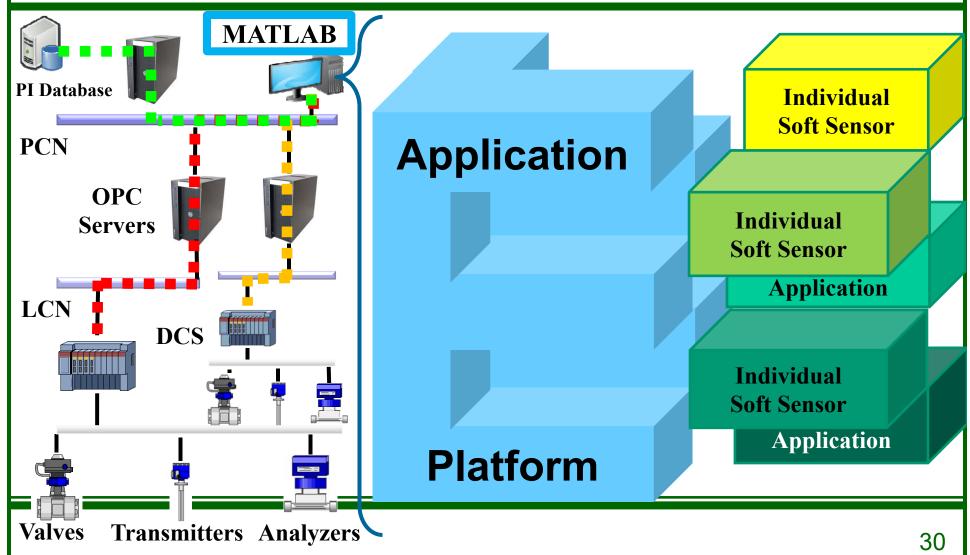


Process Data Analytics in Oil Sands



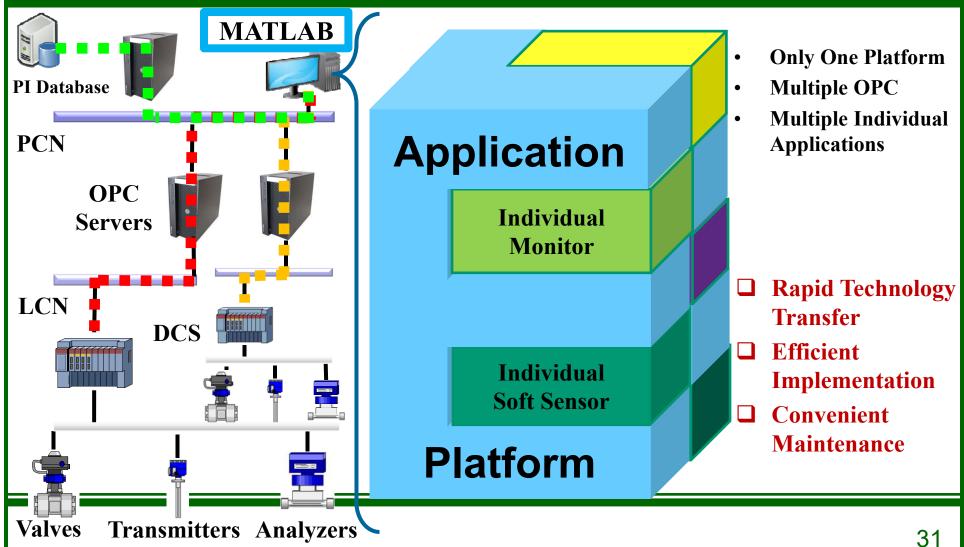


Rapid Technology Transfer Platform





Application Platform

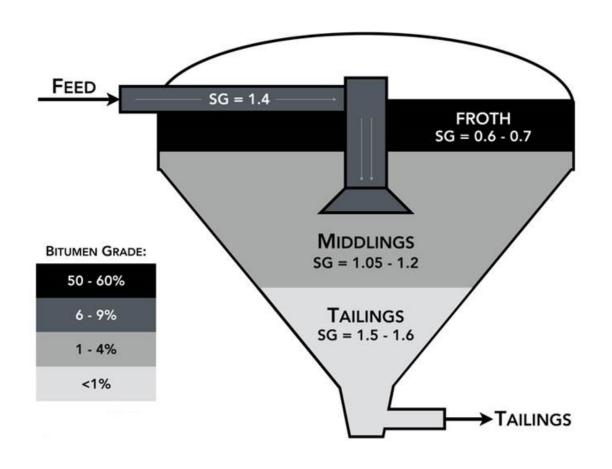




Data Analytics in Image Processing



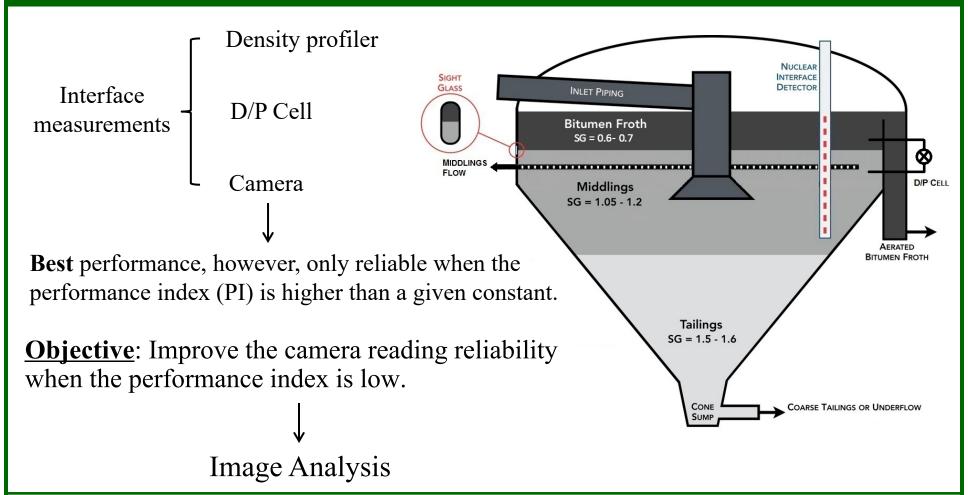
Introduction of PSV



- Three layers due to density difference
- Froth/Middling interface level is the most important control variable



PSV interface measurements





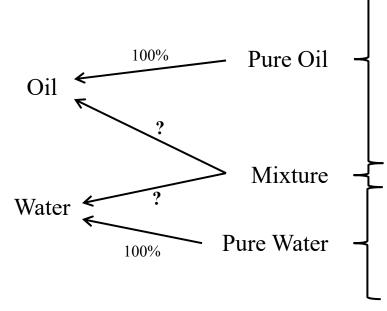
Experimental Design



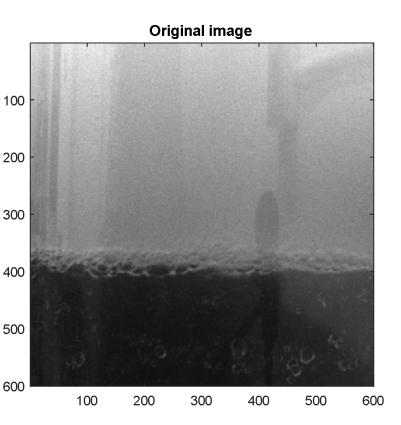


Image Captured by Camera

• The image shown on the right is the original image observed by the camera.



Objective: Segment the captured image as a binary image (+1 for oil/-1 for water/ 0 for interface)



Note: the image size for all images is (600 pixels × 600 pixels)

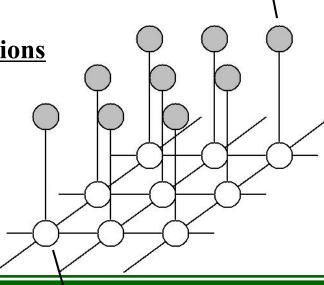


Theory of Data Based Image Analysis

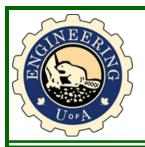
- Images can be modeled using Markov random field (MRF).
 - Each pixel is considered as a random variable (RV)
 - Each random variable (pixel) has a corresponding observation (corrupted with noise)

Aim: to recover clean pixels from noisy observations

MRF is employed to perform image segmentation and classification.



Noisy observations



Principle of MRF Estimation

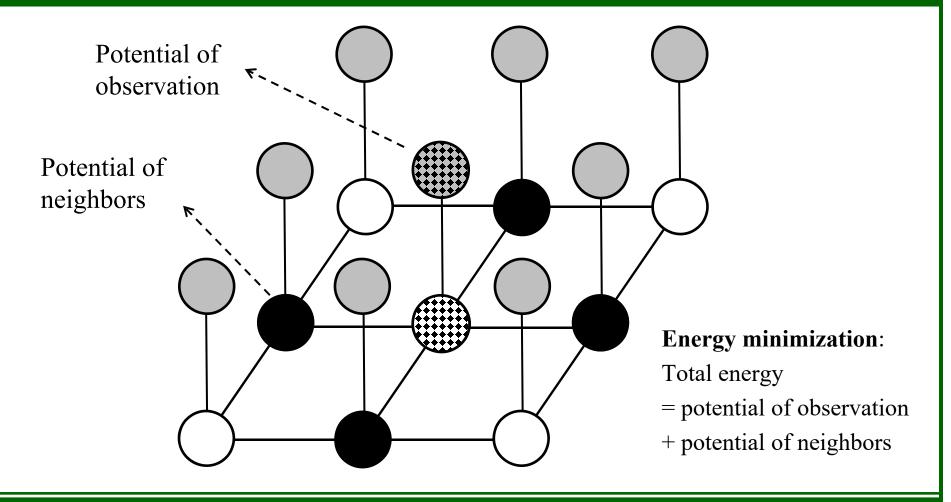
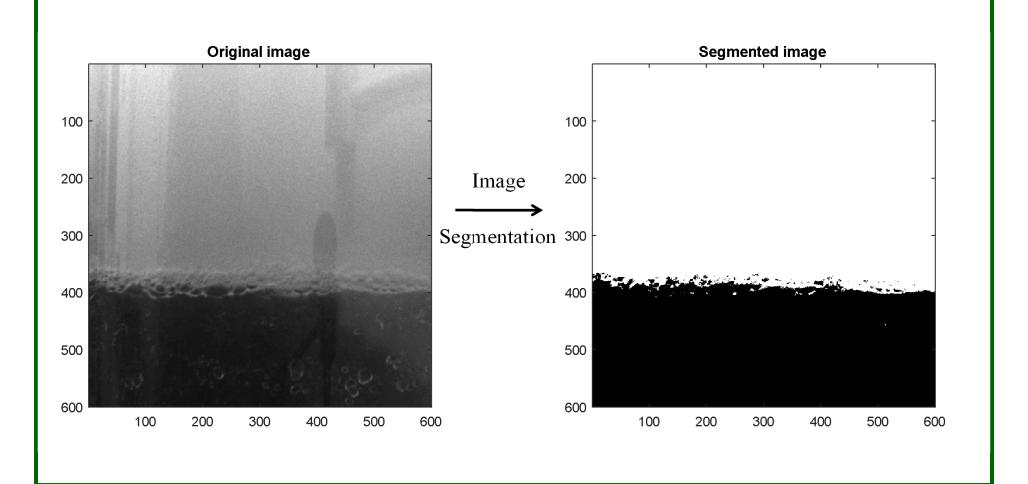


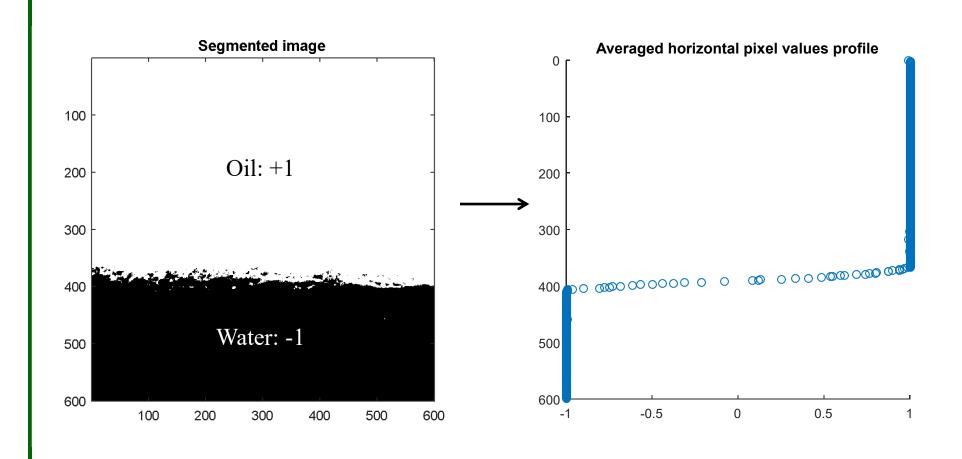


Image Segmentation



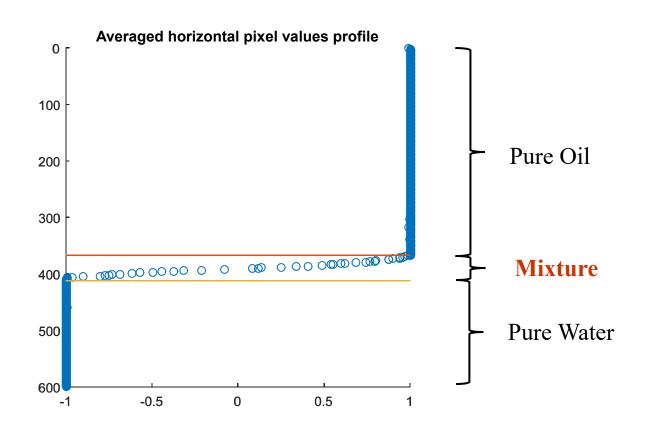


Pixel Values Profile



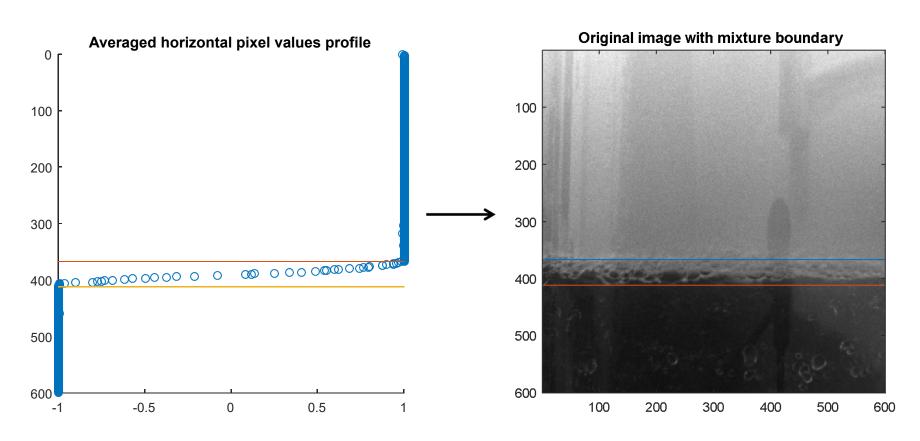


Mixture Boundary Determination





Mixture Boundary Indication



Next step: Identify the interface based on the pixel value close to zero



Interface Estimation

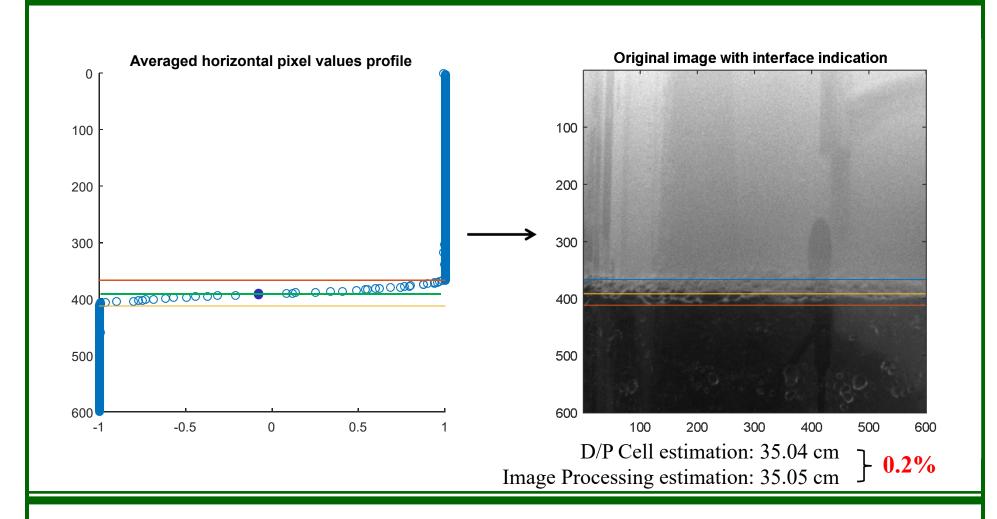
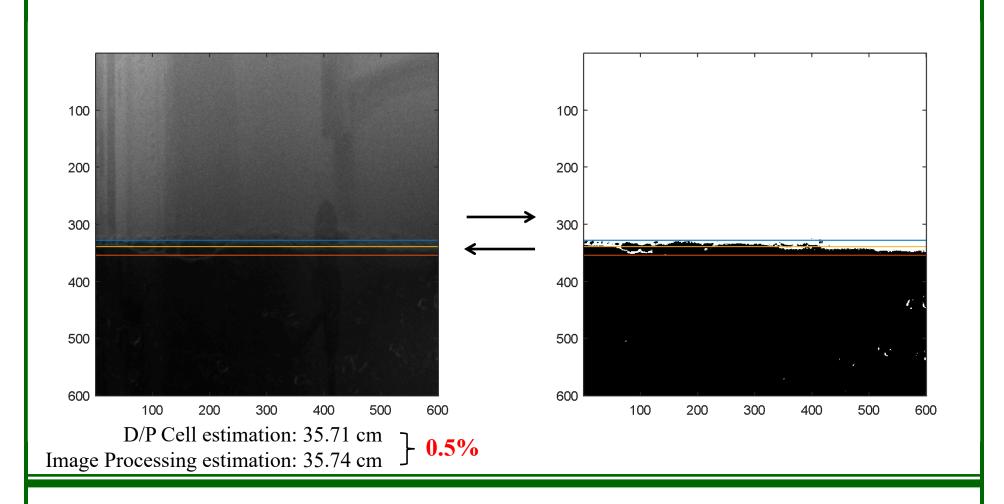




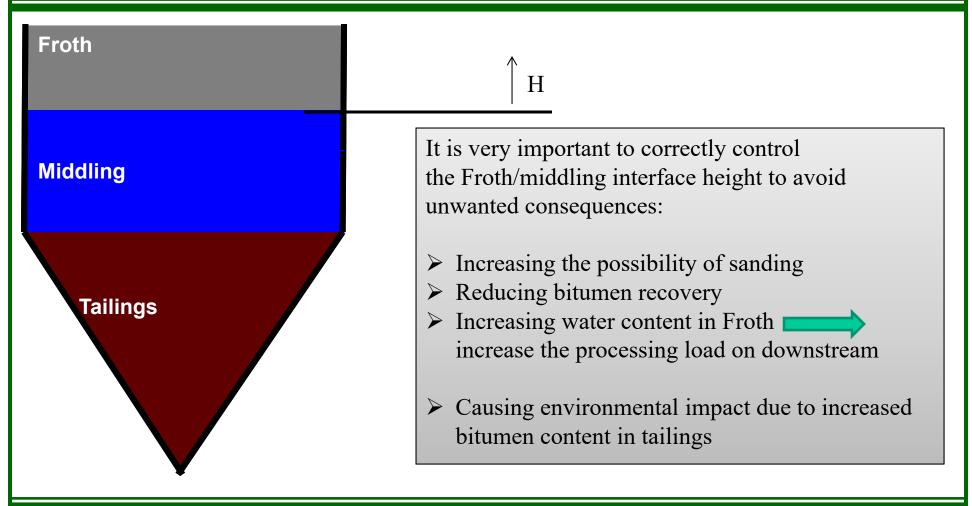
Image under Different Condition



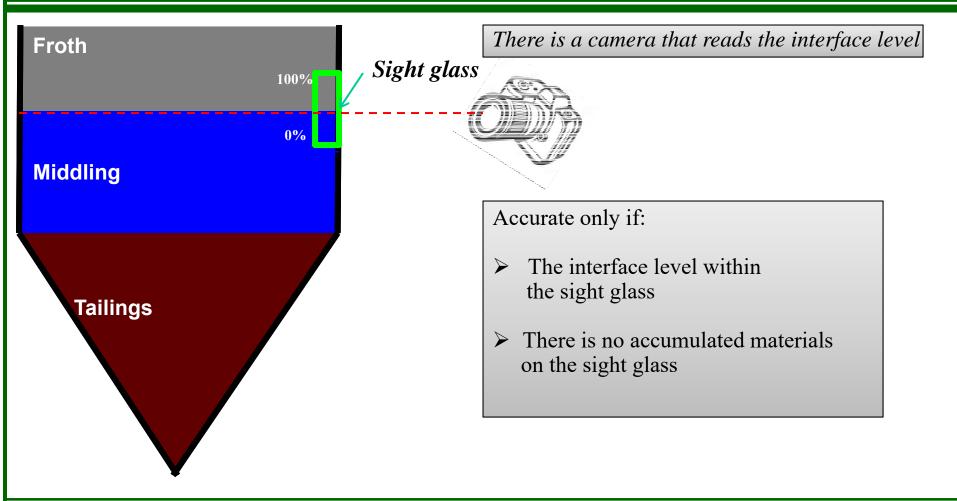


Data Synthesizing - Field Applications

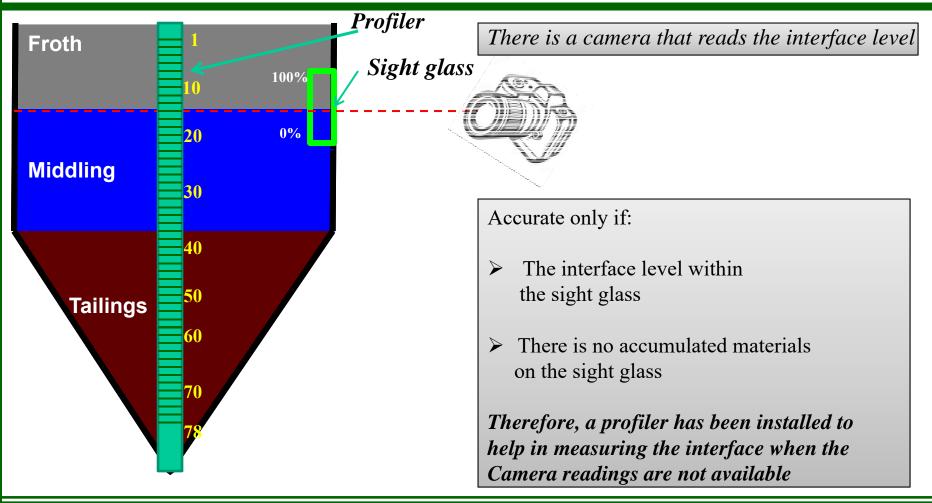




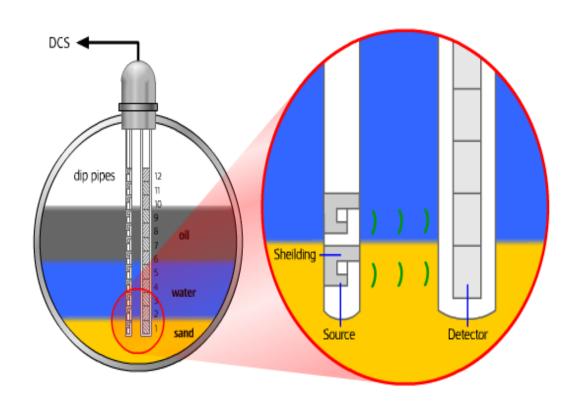








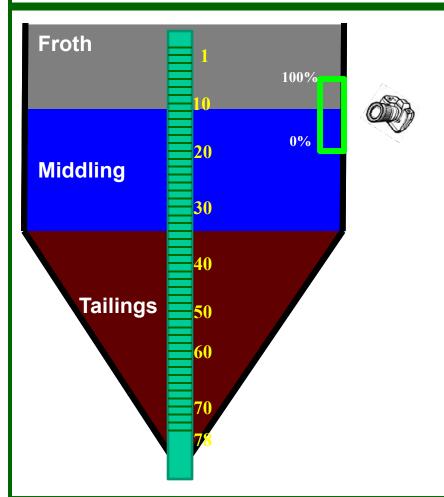




The profiler

- > Two dip pipes assembly
- A narrow dip pipe emits low energy gamma
- Another dip pipe holds an array of gamma detectors
- Due to difference in density, each phase attenuates the signal by different amounts
- These signals are transmitted to DSC as density measurements



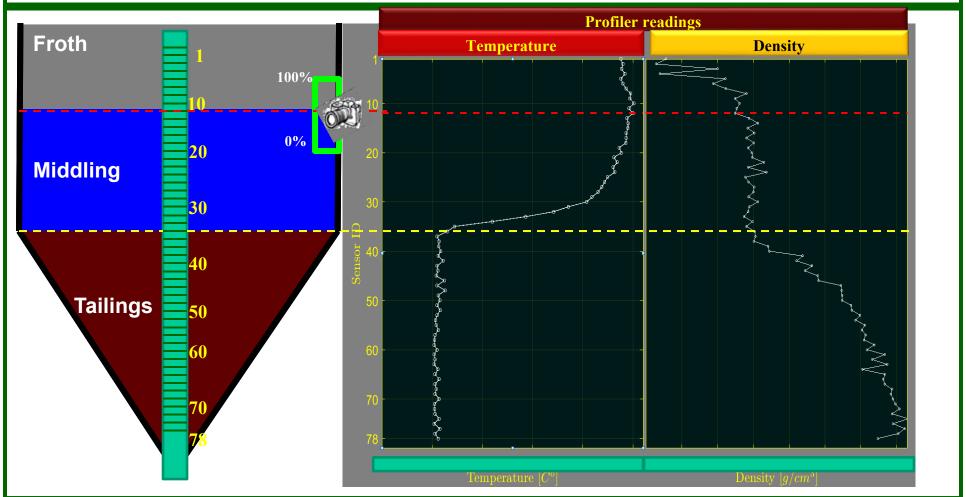


Objective:

Ensure the availability of interface level readings that is:

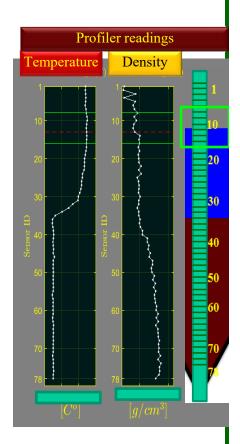
- > Continuous
- > Accurate
- > Anywhere in the PSV.



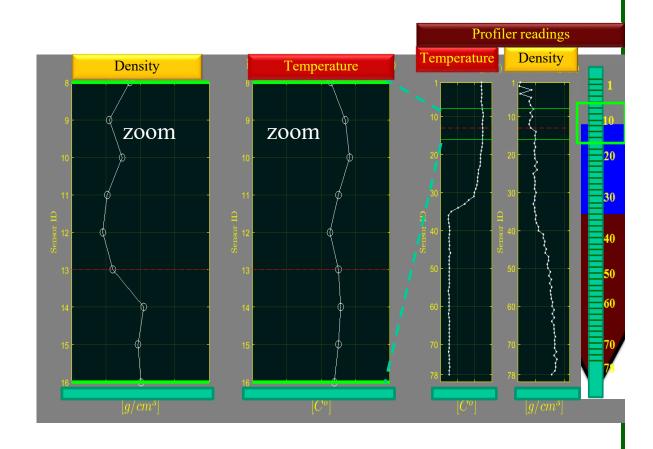


There is no clear characteristic behavior of profiler data around the interface







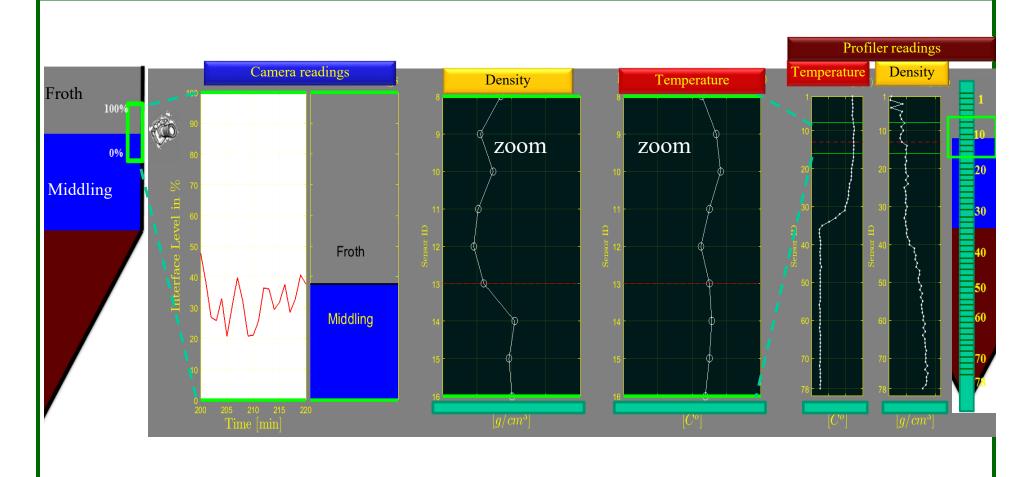


There is no clear characteristic behavior of profiler data around the interface.

The majority of them move with the interface

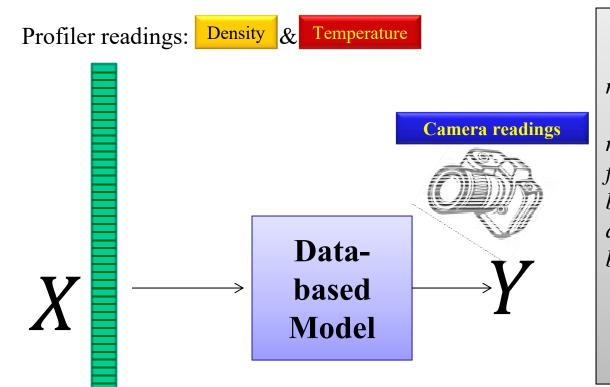








Method/Regression



We choose data-based modeling technique where:

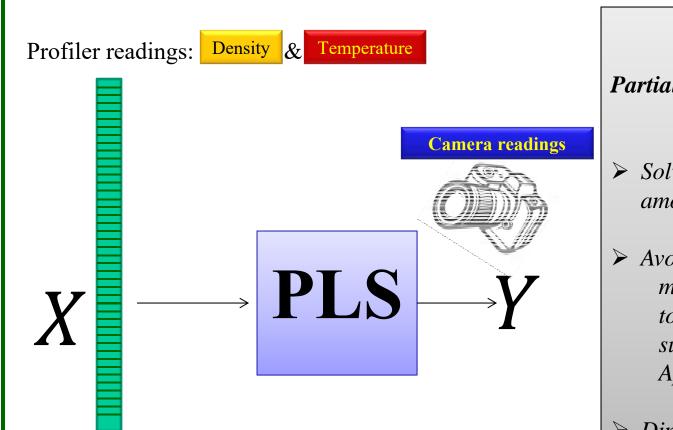
model is built to predict interface from profiler (**D** & **T**) readings by learning from the camera as an accurate reference,

by means of **regression** between:

- \triangleright Profiler data X
- > Camera readings Y



Method/Regression/PLS



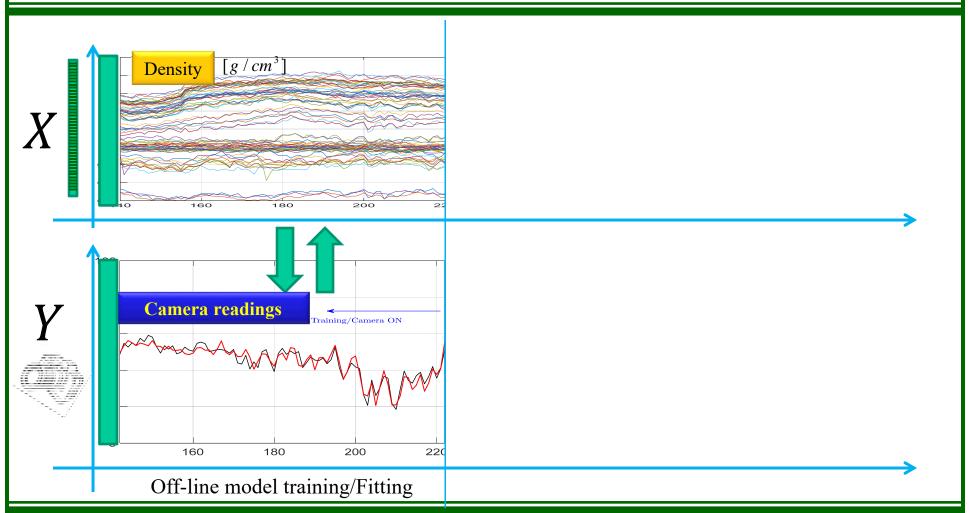
We choose:

Partial Last Squares regression (PLS)

- ➤ Solves the collinearity issues among the X variables
- ➤ Avoids inverting covariance
 matrix (XX)⁻¹ compared
 to OLS "RPLS"
 suitable for online DCS
 Application
- ➤ Dimensionality reduction

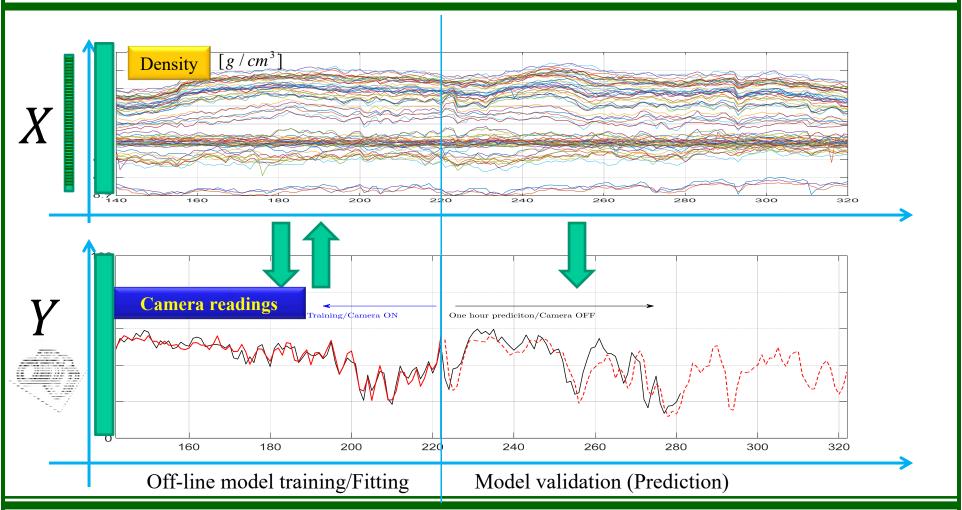


Method/Regression/PLS





Method/Regression/PLS



However, due to variations in process conditions, the off-line model becomes outdated



Method/Regression/Recursive PLS





- \triangleright Choose a representative training set (\mathbf{X}_0, Y_0)
- ➤ Calculate the covariance matrices "offline"

$$(\mathbf{X}^{\mathsf{T}}\mathbf{X})_{0}$$

$$(\mathbf{X}^{\mathsf{T}}\mathbf{y})_0$$

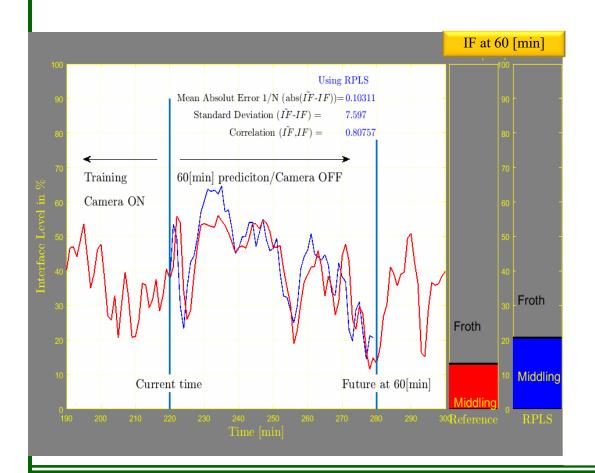
 \triangleright Update it online whenever a new sample (\mathbf{x}_t, y_t) becomes available

$$(\mathbf{X}^{\mathrm{T}}\mathbf{X})_{t} = \lambda(\mathbf{X}^{\mathrm{T}}\mathbf{X})_{t-1} + \mathbf{x}_{t}^{\mathrm{T}}\mathbf{x}_{t}$$

$$(\mathbf{X}^{\mathsf{T}}\mathbf{y})_{t} = \lambda(\mathbf{X}^{\mathsf{T}}\mathbf{y})_{t-1} + \mathbf{x}_{t}^{\mathsf{T}}y_{t}$$

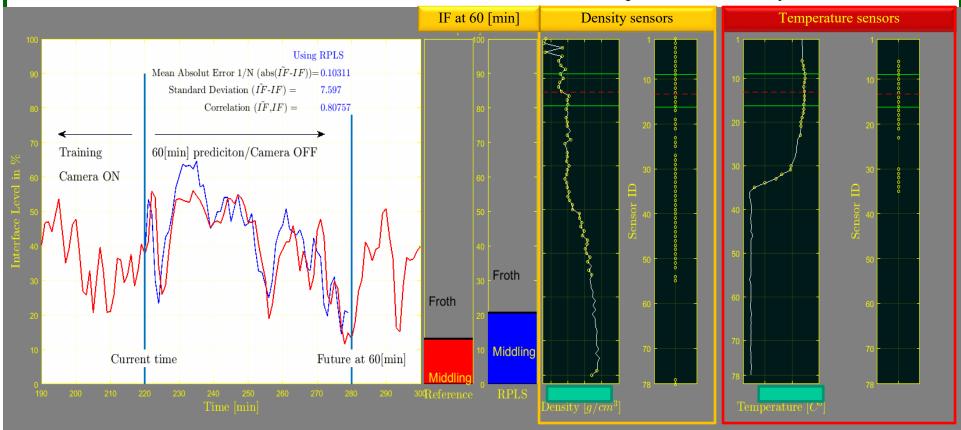
 $1 > \lambda > 0$ Forgetting factor





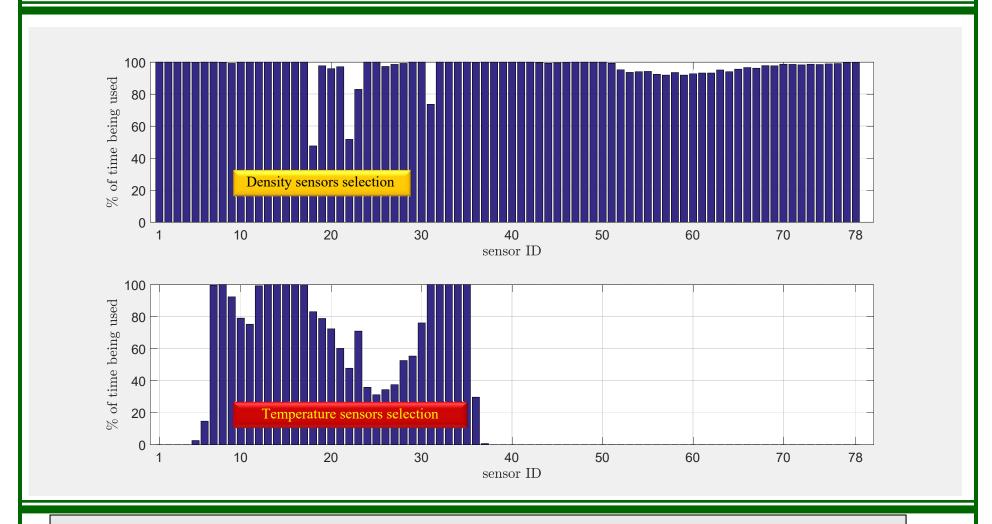


PLS helps in dimensionality reduction in X



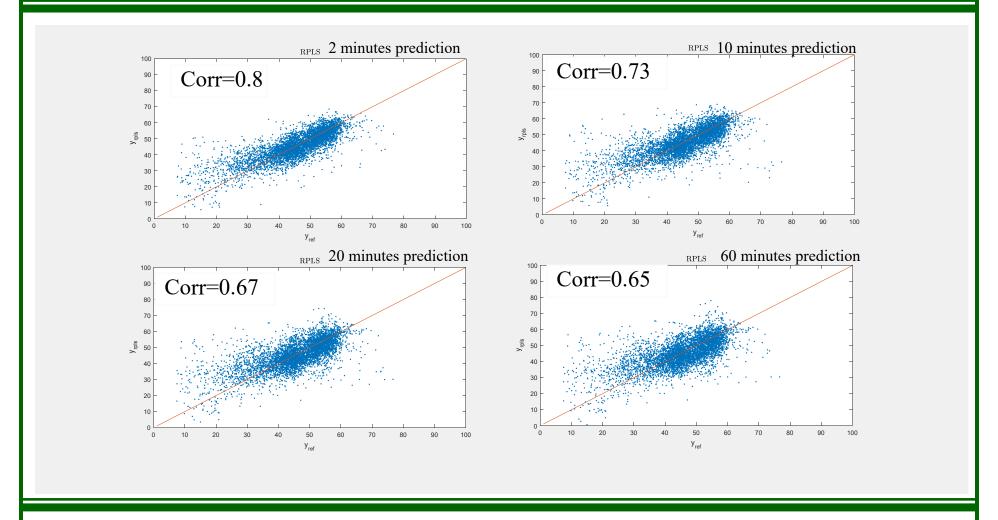
The RPLS algorithm allows to select the input variables that have the highest "importance" *Reduce dimensionality*

Results



The RPLS algorithm allows to select the input variables that have the highest "importance" **Reduce dimensionality*







Analytics Toolboxes in Progress



Soft Sensor Analytics

Data preprocess

Cumbersome

Resample, outlier detection, rearrange, normalize, detrend....

Data modeling

Complex

OLS, LASSO, RR, PCA, PLS, nonlinear regression....

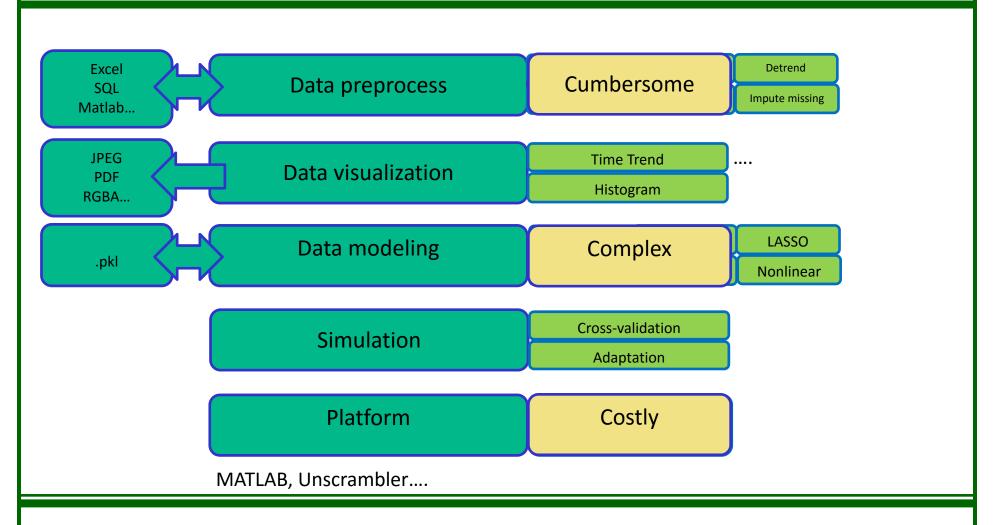
Platform

Costly

MATLAB, Unscrambler....

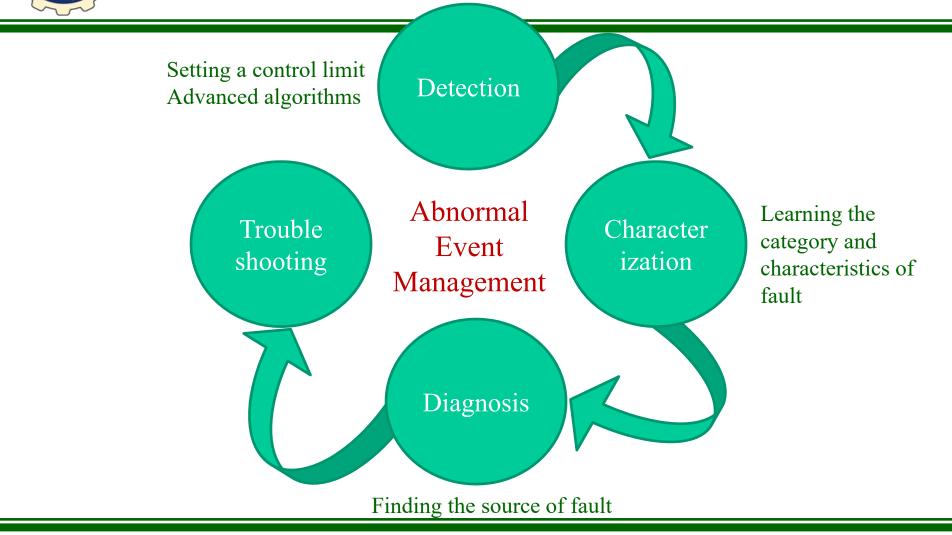


Soft Sensor Analytics



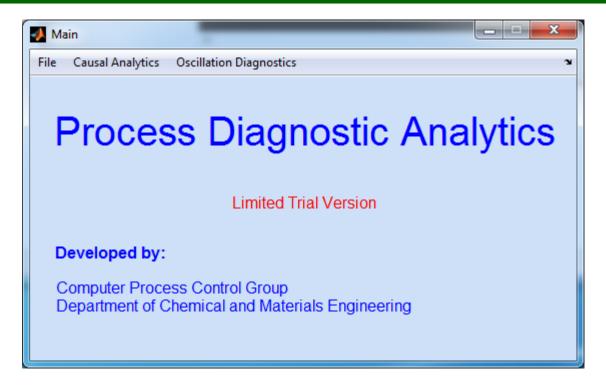


Process Diagnosis Analytics - Toolbox





Process Diagnosis Analytics - Toolbox



- Causal Analytics: Extracts causality relations among the variables from data
- Oscillation Diagnostics: Detects and characterizes oscillatory type of faults



Conclusion

- Data analytics is an emerging area of research and applications
- Great potential, demands and opportunities
- Applicable in every sector
- Opportunity for everyone



Acknowledgments

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